Machine Learning Module 3.0 - Models: Introduction

Marc-Olivier Boldi

Master in Management, Business Analytics, HEC UNIL

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Machine Learning

In ML, models are mainly used for supervised learning, the aim is

- Predict a response y: regression if numerical, classification if categorical.
- From features x = {x₁,..., x_p}: available at the moment of prediction,
- With the best possible quality: built from the data in an optimal way.

The n observed features and responses are denoted

$$(y_1, x_1), \ldots, (y_n, x_n).$$

In ML, a model consists mainly of three elements:

- A prediction formula, taking the features x, returning a prediction $\hat{y} = f(x)$ for y,
- A loss function $\mathcal{L}(y, \hat{y})$ measuring how "wrong" a prediction \hat{y} is for y.
- An algorithm which can optimize the prediction formula *f* using the observed data.

The prediction formula is a mathematical formula (sometimes a more complex algorithm) using **parameters**¹ θ , combining them with the feature *x*, returning a prediction

 $f(x; \theta).$

Thus, θ must be chosen carefully to obtain good predictions of y.

¹Also called weights, especially for Neural Networks. $\langle \Box \rangle \langle \Box \rangle \langle \Box \rangle \langle \Box \rangle$

The loss function indicates how wrong is a prediction \hat{y} of the corresponding *y*.

A classical example for regression is the square of the error:

$$\mathcal{L}(y,\hat{y})=(y-\hat{y})^2.$$

The larger $\mathcal{L}(y, \hat{y})$, the further \hat{y} is from y.

Good parameters θ must have a low loss. We want $\mathcal{L}(y, f(x; \theta))$ to be small for all (y, x). To achieve an overall quality on the whole available data base, we want θ achieving a small

$$\bar{\mathcal{L}}(\theta) = \frac{1}{n} \sum_{i=1}^{n} \mathcal{L}\{y_i, f(x_i; \theta)\}.$$

Example: with the square of the error, this is

$$\bar{\mathcal{L}}(\theta) = \frac{1}{n} \sum_{i=1}^{n} \{y_i, f(x_i - \theta)\}^2.$$

6/8

Finding the optimal $\hat{\theta}$ is done by applying an algorithm, i.e., a procedure that finds

$$\hat{ heta} = rg \min_{ heta} ar{\mathcal{L}}(heta).$$

The algorithm is often a sequential procedure. It builds a sequence $\theta_1, \theta_2, \theta_3, \ldots$ such that

$$\bar{\mathcal{L}}(heta_1) > \bar{\mathcal{L}}(heta_2) > \bar{\mathcal{L}}(heta_3) > \dots$$

Ultimately, this should reach the minimum possible $\overline{\mathcal{L}}(\theta)$.

1

Mathematical considerations

- More flexible model *f* provides better opportunity to minimize *L*. Often, this is associated with the size of θ (number of parameters).
- The algorithm may not reach the global minimum of $\overline{\mathcal{L}}$. Most algorithms cannot guaranty such results except under theoretical assumptions.
- A probabilistic interpretation: the optimal θ is obtained by minimizing the expected loss on the population of (Y, X)

$$E\left[\mathcal{L}\left\{Y,f(X;\theta)\right\}\right].$$

The data base is used to estimate it with an empirical mean

$$\hat{E}\left[\mathcal{L}\{Y, f(X; \theta)\}\right] = \frac{1}{n} \sum_{i=1}^{n} \mathcal{L}\{y_i, f(x_i; \theta)\}.$$

This estimate is minimized in turn to find an estimate of the optimal θ .

8/8